Accessible Automated Automotive Workshop Series (A3WS): Focus External Human-Machine Interfaces (eHMIs)

Mathias Haimerl

mathias.haimerl@thi.de Technische Hochschule Ingolstadt Ingolstadt, Germany Johannes Kepler Universität Linz, Austria

Andreas Löcken

andreas.loecken@carissma.eu Technische Hochschule Ingolstadt CARISSMA Institute of Automated Driving Ingolstadt, Germany

ABSTRACT

With modernizing traffic, a rise of automated vehicles (AVs) is expected. As AVs potentially need to communicate their intentions, external human-machine interfaces (eHMIs) seem to be an appropriate solution. While automotive research progresses quickly, people with special needs (PSN) are vastly underrepresented. With an aging population due to demographic changes and advances in medical treatments and with the stride towards equality and accessibility, the needs of these groups also have to be considered in the automotive domain. We provide an inclusive platform for interdisciplinary exchange on current and future topics, especially for academia, industry, and politics. This enables different perspectives with particular (but not exclusive) regard to user experience (UX) and psychology, product design, legislative concerns and, thus, support the communication and potentially founding of new topic streams. The aim is to create new interdisciplinary networks and collaborations to make future developments on vehicle-to-human (V2H) communication more inclusive.

KEYWORDS

accessibility, learning disorder, eHMI, automated vehicles, vulnerable road users

BACKGROUND

AVs are expected to alter traffic for all road users: from making traffic safer due to less human failure [12] over enabling novel non-driving related tasks within the vehicle [20] to altered communication needs for vulnerable road users such as pedestrians or bicyclists [13].

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the owner/author(s).

Veröffentlicht durch die Gesellschaft für Informatik e.V.

in K. Marky, U. Grünefeld & T. Kosch (Hrsg.):

Mensch und Computer 2022 - Workshopband, 04.-07. September 2022, Darmstadt

© 2022 Copyright held by the owner/author(s).

https://doi.org/10.18420/muc2022-mci-ws09-116

Mark Colley

mark.colley@uni-ulm.de Institute of Media Informatics, Ulm University Ulm, Germany

Andreas Riener

andreas.riener@thi.de Technische Hochschule Ingolstadt Ingolstadt, Germany

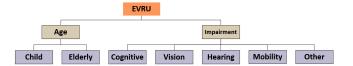


Figure 1: eVRUs as categorized by Holländer et al. [13].

eHMIs are seen as one solution to overcome the current availability of human drivers to engage with the outside world, for example, via gestures, eye-gaze, or speech [11]. Previous work on eHMIs evaluated numerous aspects of this communication: design spaces were created [7], the environment for example in the form of the sidewalk was included in the communication [5], the lack of scalability evaluations were shown [10], construction site scenarios were investigated [6], systematic comparisons were conducted [16], and anthropomorphic characteristics were introduced [3, 4].

Despite this work, the communication between AVs and vulnerable road users, especially with a focus on inclusion, is lacking [8, 9].

1.1 Especially Vulnerable Road Users

Vulnerable road users (VRUs) can be categorized as pedestrians, cyclists, and motorcyclists as done by the World Health Organization [18]. In general, VRUs are defined as not having a protective outside shield [24].

Holländer et al. [13] argued that VRUs are more diverse in the context of traffic and Human-Computer Interaction and, therefore, defined this group more granular. The first distinguishing factor is motorization (motorcyclist, personal conveyance versus pedestrian, personal conveyance, cyclist). Every defined class can be attributed "especially vulnerable" (see Figure 1). This can be due to age or disability [13]. In this workshop, we want to focus on this characteristic and help in making (future) traffic more accessible.

While it is already crucial to make traffic accessible for all people and their abilities, it will only become more important in the future with an aging population and better chances of surviving accidents and diseases. At the same time, the demographic changes already make it difficult to have enough medical and care staff to support patients more than is essential for survival. Thus, inclusive

Table 1: The preliminary schedule of our proposed workshop.

Duration	Topic
30 min	Pt. 1 Opening and participant introduction
60 min	Inspiration (Position Papers and Lightning Talks)
30 min	Morning Break
90 min	Interactive Session I
90 min	Lunch Break
90 min	Interactive Session II
30 min	Afternoon Break
30 min	Summary and Outlook

automated traffic is not only the right thing to do from a moral perspective, but also necessary to keep people with disabilities as independent as possible because of a lack of care staff that would be needed to help with basic but important tasks like shopping to getting to a doctor's appointment.

1.2 Automated Vehicles

With ongoing deployment of AVs [19], traffic is expected to change to be more automated in the near future. Besides technical challenges of automation [14], the interaction with other road users, like pedestrians or cyclists [23] depends on being efficient [15] and trusted [25]. These needs are especially important to empower PSN in daily life activities [1, 22], including using shared spaces. Lower access to mobility reduces the possibility to socialize, to have access to health care, to go shopping, or even to gain employment [2, 21]. Therefore, improved automation is seen as a key enabler to enhance participation of PSN in everyday life.

2 ORGANIZATION & SCHEDULE

Only few publications have specifically dealt with the topic of inclusive AV-VRU communication [9]. Following up the objectives and preliminary work at the *WeCARe* workshop [17], we aim at:

- Providing an interdisciplinary forum for designers, practitioners, and researchers to discuss challenges and approaches for an inclusive approach to eHMIs and create a platform for future networks.
- Discussing state-of-the-art research on inclusive eHMIs [8, 9] and how this can be enhanced and how this can be broadened
- Foster ideas and approaches to better integrate PSN into research and development of AVs
- Formulate a research agenda to support initiatives in research and practice to strengthen the accessibility of today's and future automotive designs

The key research questions we want to raise and discuss are:

- What are the main blockers hindering researchers to collaboratively work with PSN?
- How to involve PSN better in the development and design?
- What are inclusive designs in the automotive context that can leverage today's advanced technology to support PSN?

Table 1 shows the planned schedule. It is separated into an "Inspiration" session in the morning, consisting of position papers and lightning talks, accompanied by two interactive sessions.

We will send out a call for contributions over multiple channels to contacts in academia, politics and industry. A peer review (min. 2 reviewers) will be performed by the workshop organizers and volunteers from the organizers' teams.

We accept position papers in English and German, but prefer the workshop to be in German to make it easier to reach potential participants outside the MuC community. However, it will not be a problem to switch to English if the background of the participants shows that this is the more appropriate language for all.

As a unique selling point of this workshop, we expect to be able to bring together people from the medical field and representatives of people with disabilities with the typical target audience of this conference (human-machine interaction specialists and usability experts) to get closer to the real needs of people with disabilities instead of just talking about them.

3 AUDIENCE

Our target group are researchers and especially practitioners working on AVs, e.g., with a focus on eHMIs as well as experts on inclusion and accessibility. To reach this target group, we plan to promote this workshop with a dedicated website, and we will reach the community via social media channels (e.g., Twitter, Facebook, and LinkedIn) and mailing lists (e.g., GI, or ACM SIGCHI). We will set up a workshop website at https://a3ws.github.io/MuC2022/including all relevant information and the accepted position papers. We also invite Lightning Talks.

4 EXPECTED OUTCOMES

Our primary goal is to connect practitioners and researchers from different areas to enable meaningful discussions about accessibility and inclusiveness for the automotive domain. Participants will discuss, share, learn approaches for an inclusion-based approach to research in the driving domain. Additionally, novel research ideas and a network of potential collaborators should be established. The outcomes of the workshop will be made publicly available. We plan to publish accepted position papers on the workshop's website. Additionally, the workshop is intended to start collaborations for future inclusive technologies. To this end, we want to open up communication channels for future contact. As this research area is still under-reported, we see the workshop as a starting point for high-impact publications.

5 ORGANIZERS

Mathias Haimerl (corresponding author) is a PhD candidate at the Johannes Kepler Universität (JKU) Linz. His research at the Human-Computer Interaction Group (HCIG) of Technische Hochschule Ingolstadt (THI) focuses on inclusion in automated traffic.

Mark Colley is a PhD candidate at the University of Ulm in the Institute of Media Informatics. His research looks into communication possibilities between automated vehicles and vulnerable road users such as pedestrians and cyclists with a particular focus on accessibility. Mark Colley already co-organized two workshops at AutomotiveUI and MobileHCI.

Andreas Löcken is a postdoctoral researcher in the HCI group at the Technische Hochschule Ingolstadt (THI) and the CARISSMA Institute of Automated Driving (C-IAD). His research focuses on human-computer interfaces, and in particular on the interaction

between humans and automated vehicles, including the perspectives of passengers and vulnerable road users such as pedestrians. He has co-organized five workshops and a tutorial, as well as six times the AutomotiveUI conference and once MuC.

Andreas Riener is professor for Human-Machine Interaction and Virtual Reality at Technische Hochschule Ingolstadt (THI) with co-appointment at the CARISSMA Institute of Automated Driving (C-IAD). He conducts hypotheses-driven quasi-experimental research in HCI with focus on future mobility concepts. He is steering committee co-chair of ACM AutomotiveUI and chair of the ACM SIGCHI German chapter. He has co-organized several workshops at Mensch und Computer, CHI, and AutomotiveUI.

ACKNOWLEDGMENTS

M. Colley works within the project 'Interaction between automated vehicles and vulnerable road users' (Intuitiver) funded by the Ministry of Science, Research and Arts of the State of Baden-Württemberg. He is also funded by the Startup Funding B of Ulm University. A. Löcken and A. Riener are supported by the German Federal Ministry for Digital and Transport (BMDV) within the *Automated and Connected Driving* funding program under Grant No. 01MM20012J (SAVeNoW).

REFERENCES

- Susan M. Allen and Vincent Mor. 1997. The Prevalence and Consequences of Unmet Need: Contrasts between Older and Younger Adults with Disability. Medical Care 35, 11 (1997), 1132–1148.
- [2] Roger Bennett, Rohini Vijaygopal, and Rita Kottasz. 2019. Attitudes towards autonomous vehicles among people with physical disabilities. *Transportation Research Part A: Policy and Practice* 127 (2019), 1–17.
- [3] Chia-Ming Chang, Koki Toda, Daisuke Sakamoto, and Takeo Igarashi. 2017. Eyes on a Car: An Interface Design for Communication between an Autonomous Car and a Pedestrian. In Proceedings of the 9th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (AutomotiveUI '17). Association for Computing Machinery, New York, NY, USA, 65–73. https://doi.org/10.1145/3122986_3122989
- [4] Mark Colley, Jan Henry Belz, and Enrico Rukzio. 2021. Investigating the Effects of Feedback Communication of Autonomous Vehicles. In 13th International Conference on Automotive User Interfaces and Interactive Vehicular Applications. Association for Computing Machinery, New York, NY, USA, 263–273. https://doi.org/10.1145/3409118.3475133
- [5] Mark Colley, Surong Li, and Enrico Rukzio. 2021. Increasing Pedestrian Safety Using External Communication of Autonomous Vehicles for Signalling Hazards. In Proceedings of the 23rd International Conference on Mobile Human-Computer Interaction. Association for Computing Machinery, New York, NY, USA, Article 20, 10 pages. https://doi.org/10.1145/3447526.3472024
- [6] Mark Colley, Stefanos Can Mytilineos, Marcel Walch, Jan Gugenheimer, and Enrico Rukzio. 2020. Evaluating Highly Automated Trucks as Signaling Lights. In 12th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (AutomotiveUI '20). Association for Computing Machinery, New York, NY, USA, 111–121. https://doi.org/10.1145/3409120.3410647
- [7] Mark Colley and Enrico Rukzio. 2020. A Design Space for External Communication of Autonomous Vehicles. In 12th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (Virtual Event, DC, USA) (AutomotiveUI '20). Association for Computing Machinery, New York, NY, USA, 212–222. https://doi.org/10.1145/3409120.3410646
- [8] Mark Colley, Marcel Walch, Jan Gugenheimer, Ali Askari, and Enrico Rukzio. 2020. Towards Inclusive External Communication of Autonomous Vehicles for Pedestrians with Vision Impairments. In Proceedings of the 2020 CHI Conference on Human Factors in Computing Systems (CHI '20). Association for Computing Machinery, New York, NY, USA, 1–14. https://doi.org/10.1145/3313831.3376472 Zentrales Paper für Bline Menschen.
- [9] Mark Colley, Marcel Walch, Jan Gugenheimer, and Enrico Rukzio. 2019. Including People with Impairments from the Start: External Communication of Autonomous Vehicles. In Proceedings of the 11th International Conference on Automotive User Interfaces and Interactive Vehicular Applications: Adjunct Proceedings (AutomotiveUI '19). Association for Computing Machinery, New York, NY, USA, 307–314. https://doi.org/10.1145/3349263.3351521

- [10] Mark Colley, Marcel Walch, and Enrico Rukzio. 2020. Unveiling the Lack of Scalability in Research on External Communication of Autonomous Vehicles. In Extended Abstracts of the 2020 CHI Conference on Human Factors in Computing Systems (CHI EA '20). Association for Computing Machinery, New York, NY, USA, 1–9. https://doi.org/10.1145/3334480.3382865
- [11] Debargha Dey, Azra Habibovic, Andreas Löcken, Philipp Wintersberger, Bastian Pfleging, Andreas Riener, Marieke Martens, and Jacques Terken. 2020. Taming the eHMI Jungle: A Classification Taxonomy to Guide, Compare, and Assess the Design Principles of Automated Vehicles' External Human-Machine Interfaces. Transportation Research Interdisciplinary Perspectives 7 (Aug. 2020), 100174. https://doi.org/10.1016/j.trip.2020.100174
- [12] Daniel J. Fagnant and Kara Kockelman. 2015. Preparing a Nation for Autonomous Vehicles: Opportunities, Barriers and Policy Recommendations. *Transportation Research Part A: Policy and Practice* 77 (July 2015), 167–181. https://doi.org/10.1016/j.tra.2015.04.003
- [13] Kai Holländer, Mark Colley, Enrico Rukzio, and Andreas Butz. 2021. A Taxonomy of Vulnerable Road Users for HCI Based On A Systematic Literature Review. In Proceedings of the 2021 CHI Conference on Human Factors in Computing Systems (CHI '21). Association for Computing Machinery, Yokohama, Japan, 1–13. https://doi.org/10.1145/1122445.1122456
- [14] Alessia Knauss, Jan Schroeder, Christian Berger, and Henrik Eriksson. 2017. Software-related challenges of testing automated vehicles. In Proceedings of the 39th International Conference on Software Engineering Companion (ICSE-C '17). IEEE Press, Buenos Aires, Argentina, 328–330. https://doi.org/10.1109/ICSE-C.2017.67
- [15] Yee Mun Lee, Ruth Madigan, Jorge Garcia, Andrew Tomlinson, Albert Solernou, Richard Romano, Gustav Markkula, Natasha Merat, and Jim Uttley. 2019. Understanding the Messages Conveyed by Automated Vehicles. In Proceedings of the 11th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (Automotive UI '19). Association for Computing Machinery, New York, NY, USA, 134–143. https://doi.org/10.1145/3342197.3344546
- [16] Andreas Löcken, Carmen Golling, and Andreas Riener. 2019. How Should Automated Vehicles Interact with Pedestrians? A Comparative Analysis of Interaction Concepts in Virtual Reality. In Proceedings of the 11th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (Utrecht, Netherlands) (Automotive U '19). Association for Computing Machinery, New York, NY, USA, 262–274. https://doi.org/10.1145/3342197.3344544
- [17] Andreas Löcken, Mark Colley, Andrii Matviienko, Kai Holländer, Debargha Dey, Azra Habibovic, Andrew L Kun, Susanne Boll, and Andreas Riener. 2020. WeCARe: Workshop on Inclusive Communication between Automated Vehicles and Vulnerable Road Users. In 22nd International Conference on Human-Computer Interaction with Mobile Devices and Services (MobileHCI '20). Association for Computing Machinery, New York, NY, USA, 1–5. https://doi.org/10.1145/3406324.3424587
- [18] World Health Organization. 2019. Protecting vulnerable road users. https://www.who.int/china/activities/protecting-vulnerable-road-users. [Online; accessed 24-FEBRUARY-2022].
- [19] Andreas Riener, Alexandra Appel, Wolfgang Dorner, Thomas Huber, Jan Christopher Kolb, and Harry Wagner (Eds.). 2020. Autonome Shuttlebusse im ÖPNV: Analysen und Bewertungen zum Fallbeispiel Bad Birnbach aus technischer, gesellschaftlicher und planerischer Sicht. Springer Berlin Heidelberg, Berlin, Heidelberg. https://doi.org/10.1007/978-3-662-59406-3
- [20] Clemens Schartmüller, Sayan Sarcar, Andreas Riener, Andrew L. Kun, Orit Shaer, Linda Ng Boyle, and Shamsi Iqbal. 2020. Automated Cars as Living Rooms and Offices: Challenges and Opportunities. In Extended Abstracts of the 2020 CHI Conference on Human Factors in Computing Systems (CHI EA '20). Association for Computing Machinery, Honolulu, HI, USA, 1–4. https://doi.org/10.1145/ 3334480 3381054
- [21] Paul Stenquist. 2014. In Self-Driving Cars, a Potential Lifeline for the Disabled. https://www.nytimes.com/2014/11/09/automobiles/in-self-driving-carsa-potential-lifeline-for-the-disabled.html?emc=eta1
- [22] Lois M. Verbrugge and Purvi Sevak. 2002. Use, Type, and Efficacy of Assistance for Disability. The Journals of Gerontology: Series B 57, 6 (Nov 2002), S366–S379. https://doi.org/10.1093/geronb/57.6.S366
- [23] Tamara von Sawitzky, Philipp Wintersberger, Andreas Löcken, Anna-Katharina Frison, and Andreas Riener. 2020. Augmentation Concepts with HUDs for Cyclists to Improve Road Safety in Shared Spaces. In Extended Abstracts of the 2020 CHI Conference on Human Factors in Computing Systems (CHI EA '20). Association for Computing Machinery, Honolulu, HI, USA, 1–9. https://doi.org/10.1145/ 3334480.3383022
- [24] Fred Wegman, Letty Aarts, and Charlotte Bax. 2008. Advancing sustainable safety: National road safety outlook for The Netherlands for 2005–2020. Safety Science 46, 2 (2008), 323–343.
- [25] Philipp Wintersberger, Hannah Nicklas, Thomas Martlbauer, Stephan Hammer, and Andreas Riener. 2020. Explainable Automation: Personalized and Adaptive UIs to Foster Trust and Understanding of Driving Automation Systems. In 12th International Conference on Automotive User Interfaces and Interactive Vehicular Applications (AutomotiveUI '20). Association for Computing Machinery, New York, NY, USA, 252–261. https://doi.org/10.1145/3409120.3410659